
University of Saskatchewan
Department of Electrical and Computer Engineering

Final Examination of **EE362: Digital Signal Processing**
December 16, 2020
3 hours

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10 points

1. Consider the discrete-time system shown in Fig. 1. For each of the following input signals $x[n]$, indicate (and justify) whether the output $x_r[n] = x[n]$.

- $x[n] = \cos(\pi n/4)$
- $x[n] = \cos(\pi n/2)$
- $x[n] = (\sin(\pi n/8))^2 / (\pi n)^2$, **hint:** Use the modulation property of the Fourier transform to find $X(e^{j\omega})$.

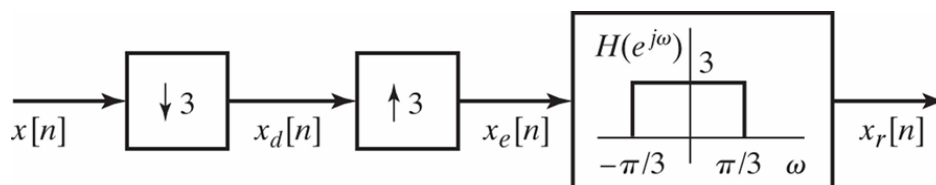


Figure 1: Discrete-time system.

4 points

2. Show that the function $x[n] = \alpha^n$, where α is a complex constant, is an eigenfunction of an LTI discrete-time system. Is $y[n] = \alpha^n u[n]$, where $u[n]$ is the unit step sequence, also an eigenfunction of an LTI discrete-time system?

6 points

3. Determine a closed-form expression for the frequency response $H(e^{j\omega})$ of the LTI discrete-time system characterized by the following impulse response

$$h[n] = \delta[n] - \alpha\delta[n - 5],$$

where $|\alpha| < 1$.

- Plot the pole-zero diagram and indicate the ROC for the system function.
- Make a carefully labeled sketch of the magnitude $|H(e^{j\omega})|$. What are the maximum and the minimum values of its magnitude response? Use the pole-zero locations to explain why the frequency response looks as it does.
- State whether the system is stable, causal, and minimum-phase system. Justify your answer.
- Determine a closed-form expression for the frequency response $G(e^{j\omega})$ of the LTI discrete-time system characterized by an impulse response

$$g[n] = h[n] * h[n] * h[n],$$

where $*$ denotes the convolution.

10 points

4. Consider the cascade of the following three causal first-order LTI discrete-time systems:

$$H_1(z) = \frac{2 + 0.1z^{-1}}{1 + 0.4z^{-1}}, \quad H_2(z) = \frac{3 + 0.2z^{-1}}{1 - 0.3z^{-1}}, \quad H_3(z) = \frac{1}{1 - 0.2z^{-1}}.$$

- Determine the transfer function of the overall system as a ratio of two polynomials in z^{-1} .
 - Determine the difference equation characterizing the overall system.
 - Develop the realization of the overall system with each section realized in direct form II.
 - Develop a parallel form I realization of the overall system.
 - Determine the impulse response of the overall system in closed form.
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10 points

5. A digital low-pass filter is required to meet the following specifications:

- Passband gain between 0 dB and -0.5 dB
- Passband edge $\pi/3$
- Stopband attenuation of at least -40 dB
- Stopband edge $\pi/2$

The filter is to be designed by performing a bilinear transformation on an analog system function.

- Determine what order Butterworth design must be used to meet the specifications in the digital implementations.
Hint: You do not need to evaluate the system function or calculate the Butterworth cutoff frequency.
 - Which specifications (passband vs. stopband) will you meet exactly and which specifications (passband vs stopband) will you exceed. Justify your answer.
 - Repeat (b) if the Butterworth order in (a) was obtained by the impulse invariance method.
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5 points

6. For the lowpass filter specifications in Fig. 2, assume that $w_p = 0.63\pi$, $w_s = 0.65\pi$, $\delta_{p1} = \delta_{p2} = 0.05$, and $\delta_s = 0.1$. Design an FIR filter to meet these specifications by applying a Kaiser window to the impulse response $h_d[n]$ for the ideal discrete-time lowpass filter with cutoff $w_c = 0.64\pi$. Find the values of β and M required to satisfy these specifications.

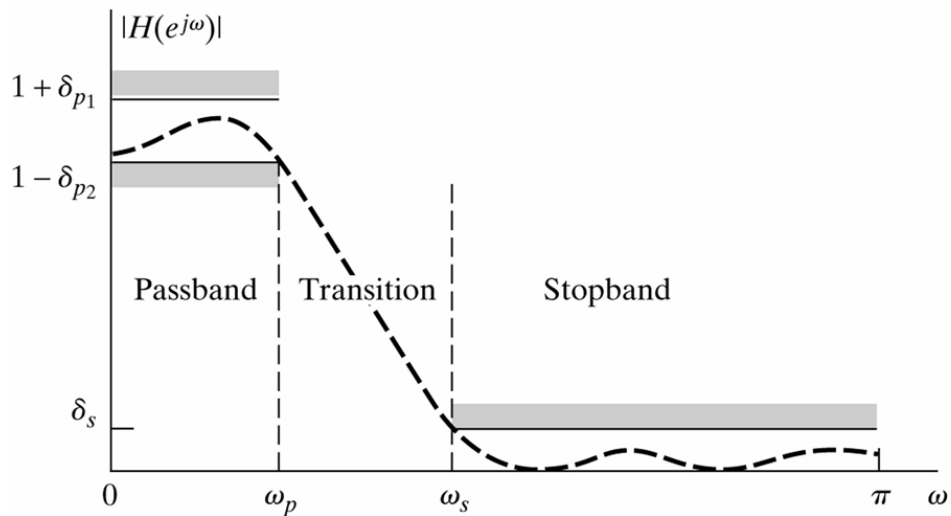


Figure 2: Lowpass filter tolerance scheme

5 points

7. Let $H(z)$ be the transfer function of a lowpass digital filter with a passband edge at w_p , stopband edge at w_s , passband ripple of δ_p , and stopband ripple of δ_s as indicated in Fig. 2. Consider a cascade of two identical filters each with a transfer function $H(z)$. What are the passband and stopband ripples of the cascade at w_p and w_s , respectively? Generalize the results for a cascade of M identical sections.

Good luck ...